## **IN THE CLAIMS:**

## **Listing of Claims**

This listing of claims replaces all prior versions, and listings, of claims in the application. Currently amended claims are shown with additions <u>underlined</u> and deletions in strikethrough text. Please cancel claims 2, 4, 13-16, 20, 23, 28, 36-38 and 40 without prejudice to or disclaimer of the subject matter therein. Please add new claims 41-48. No new matter is added by this amendment.

- 1. (Currently amended) A method comprising:
  - of a body part, at least one of the images image from the plurality of images (a) depicting a non-tissue internal reference marker, (b) being linked to associated with non-tissue internal reference marker positional information, and (e) being at least 2-dimensional;
  - associating a separate transformation from a tracking space to an image space with each image in the dataset;
  - reference marker and a position of the non-tissue internal reference marker; and outputting data values associated with a display of an image from the plurality of images.
- 2. (Canceled)
- 3. (Currently amended) The method of claim 1, where wherein each image (a) depicts the non-tissue internal reference marker, and (b) is linked to non-tissue internal reference marker positional information.
- 4. (Canceled)

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5. (Currently amended) The method of claim 1, where wherein the images are 3-dimensional

computed tomography (CT) images.

6. (Currently amended) The method of claim 1, where-wherein the images are 3-dimensional

magnetic resonance imaging (MRI) images.

7. (Currently amended) The method of claim 1, where wherein the images are 2-dimensional

fluoroscopy images.

8. (Currently amended) The method of claim 21, further comprising wherein the creating the

dataset includes:

loading a gated dataset into a memory, the gated data set dataset including the plurality of

images, at least one image from the plurality of the images (a) depicting the non-

tissue internal reference marker, and (b) being linked to associated with a sample

of a first periodic human characteristic signal.

9. (Currently amended) The method of claim 8, where wherein each image from the plurality of

images (a) depicts the non-tissue internal reference marker, and (b) is linked to associated with a

sample of a first periodic human characteristic signal.

10. (Currently amended) The method of claim 8, further comprising:

receiving a second periodic human characteristic signal; and

comparing a sample of the second periodic human characteristic signal to the sample of

the first periodic human characteristic signal[[;]].

11. (Currently amended) The method of claim 10, where wherein the first and second periodic

human characteristic signals are electrocardiogram (ECG) signals.

12. (Currently amended) The method of claim 10, further comprising:

recognizingidentifying a sample of the second periodic human characteristic signal that

matches the sample of the first periodic human characteristic signal; and

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receiving (a) data associated with a position of an external reference marker and (b) data

associated with a position of the non-tissue internal reference marker.

13.-16. (Canceled)

17. (Currently amended) The method of elaim 13 claim 1, further comprising:

receiving image space coordinates of the non-tissue internal reference marker in the

image linked to associated with the dataset vector.

18. (Currently amended) The method of claim 17, further comprising:

calculating a transformation from the separate transformations using the image space

coordinates and the tracking space coordinates.

19. (Currently amended) The method of claim 18, further comprising:

associating the transformation with the image linked to associated with the dataset vector.

20. (Canceled)

21. (Currently amended) The method of claim 19, further comprising:

receiving data associated with a current position of the external reference marker;

receiving data associated with a current position of the non-tissue internal reference

marker:

calculating a current vector using the data associated with the current positions position of

the external reference marker and the data associated with the current position of

the non-tissue internal reference marker;

identifying a match dataset vector (MDV), the MDV being the dataset vector most

similar to the current vector, the MDV being linked to associated with an image

from the dataset;

receiving a current position of an instrument reference marker coupled to an instrument;

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applying the transformation associated with the image linked to associated with the MDV to the current position of the instrument reference marker, thus transforming the current position of the instrument reference marker into image space; and superimposing a representation of the instrument on the image linked to associated with

superimposing a representation of the instrument on the image linked to associated with the MDV.

22. (Currently amended) The method of elaim 15 claim 1, further comprising:

receiving data associated with a current position of the external reference marker;

receiving <u>data associated with</u> a current position of the non-tissue internal reference marker;

calculating a current vector using the <u>data associated with the current positions position of</u>

the external reference marker and the data associated with the current position of
the non-tissue internal reference marker;

identifying a match dataset vector (MDV), the MDV being the dataset vector most similar to the current vector, the MDV being linked to associated with an image from the dataset;

receiving a current position of an instrument reference marker coupled to an instrument; applying the transformation associated with the image linked to associated with the MDV to the current position of the instrument reference marker, thus transforming the current position of the instrument reference marker into image space; and superimposing a representation of the instrument on the image linked to associated with the MDV, before outputting data values associated with the display.

## 23. (Canceled)

24. (Currently amended) A method comprising:

receiving a position of an instrument reference marker coupled to an instrument; transforming the position into image space using <u>data associated with</u> a position of a non-tissue internal reference marker implanted in a patient; and

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superimposing a representation of the instrument on an image in which the non-tissue internal reference marker appears, the image being selected based on a look-up

table having data associated with a plurality of images.

25. (Currently amended) The method of claim 24, where wherein the image was taken using

fluoroscopy.

26. (Currently amended) The method of claim 24, where wherein the image was taken using

computed tomography (CT).

27. (Currently amended) The method of claim 24, where-wherein the image was taken using

magnetic resonance imaging (MRI).

28. (Canceled)

29. (Currently amended) The method of elaim 28claim 24, further comprising wherein the

transforming the position includes:

calculating the a transformation using image space coordinates and the tracking space

coordinates of the internal reference marker in the image.

30. (Currently amended) The method of claim 29, further comprising:

linking associating the transformation to with the image.

31. (Currently amended) The method of claim 30, further comprising:

loading the transformation into a memory.

32. (Currently amended) The method of claim 24, further comprising:

before the superimposing, receiving an image signal that includes the image.

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33. (Currently amended) The method of claim 32, further comprising:

receiving <u>data associated with</u> a position of the non-tissue internal reference marker in the image.

34. (Currently amended) The method of claim 33, further comprising:

calculating a vector using the position of the non-tissue internal reference marker and an external reference marker.

35. (Currently amended) The method of claim 34, further comprising:

linking associating the vector with the image.

36.-38. (Canceled)

39. (Currently amended) A method comprising:

receiving an image signal that includes <u>a plurality of images</u>, each image <u>from the plurality of images</u> depicting a non-tissue internal reference marker, the <u>plurality</u> of images associated with a cyclical movement of a body part;

receiving <u>data associated with a position</u> of the non-tissue internal reference marker in one of the images (image I1);

calculating a vector using the position of the non-tissue internal reference marker and an external reference marker;

linkingassociating the vector with an-the image I1;

linking associating a transformation from tracking space to image space with the image I1;

receiving a current position of an instrument reference marker coupled to an instrument; applying the transformation to the current position of the instrument reference marker; and

superimposing a representation of the instrument on the image I1.

40. (Canceled)

41. (New) A processor-readable medium storing code representing instructions to cause a processor to perform a process, the code comprising code to:

create a dataset that includes a plurality of images associated with a cyclical movement of a body part, at least one image from the plurality of images depicting a non-tissue internal reference marker, being associated with non-tissue internal reference marker positional information, and being at least 2-dimensional;

associate a separate transformation from a tracking space to an image space with each image in the dataset;

calculate for each image in the dataset a dataset vector using a position of an external reference marker and a position of the non-tissue internal reference marker; and output data values associated with a display of an image from the plurality of images.

42. (New) The processor-readable medium of claim 41, wherein the code to create the dataset includes code to:

load a gated dataset into a memory, the gated dataset including the plurality of images, at least one image from the plurality of images depicting the non-tissue internal reference marker, and being associated with a sample of a first periodic human characteristic signal.

43. (New) The processor-readable medium of claim 42, further comprising code to:
receive a second periodic human characteristic signal; and
compare a sample of the second periodic human characteristic signal to the sample of the
first periodic human characteristic signal.

44. (New) The processor-readable medium of claim 42, further comprising code to:

identify a sample of the second periodic human characteristic signal that matches the sample of the first periodic human characteristic signal; and

receive data associated with a position of an external reference marker and data associated with a position of the non-tissue internal reference marker.

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45. (New) The processor-readable medium of claim 41, further comprising code to:
receive data associated with a current position of the external reference marker;
receive data associated with a current position of the non-tissue internal reference marker;
calculate a current vector using the data associated with the current position of the
external reference marker and the data associated with the current position of the
non-tissue internal reference marker;

identify a match dataset vector (MDV), the MDV being the dataset vector most similar to the current vector, the MDV being associated with an image from the dataset; receive a current position of an instrument reference marker coupled to an instrument; apply the transformation associated with the image associated with the MDV to the current position of the instrument reference marker, thus transforming the current position of the instrument reference marker into image space; and superimposing a representation of the instrument on the image associated with the MDV.

- 46. (New) The processor-readable medium of claim 41, further comprising code to: receive data associated with a current position of the external reference marker; receive data associated with a current position of the non-tissue internal reference marker; calculate a current vector using the data associated with the current positions position of the external reference marker and the data associated with the current position of the non-tissue internal reference marker;
  - identify a match dataset vector (MDV), the MDV being the dataset vector most similar to the current vector, the MDV being linked to associated with an image from the dataset;

receive a current position of an instrument reference marker coupled to an instrument; apply the transformation associated with the image linked to associated with the MDV to the current position of the instrument reference marker, thus transforming the current position of the instrument reference marker into image space; and superimpose a representation of the instrument on the image linked to associated with the MDV, before outputting data values associated with the display.

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47. (New) A processor-readable medium storing code representing instructions to cause a processor to perform a process, the code comprising code to:

receive data associated with a position of an instrument reference marker coupled to an instrument;

transform the data associated with the position into image space using data associated with a position of a non-tissue internal reference marker implanted in a patient; and

superimposing a representation of the instrument on an image in which the non-tissue internal reference marker appears, the image being selected based on a look-up table having data associated with a plurality of images.

48. (New) A processor-readable medium storing code representing instructions to cause a processor to perform a process, the code comprising code to:

receive an image signal that includes a plurality of images, each image from the plurality of images depicting a non-tissue internal reference marker, the plurality of images associated with a cyclical movement of a body part;

receive data associated with a position of the non-tissue internal reference marker in one of the images (image I1);

calculate a vector using the position of the non-tissue internal reference marker; associate the vector with the image I1;

associate a transformation from tracking space to image space with the image I1; receive a current position of an instrument reference marker coupled to an instrument; apply the transformation to the current position of the instrument reference marker; and superimpose a representation of the instrument on the image I1.